



Internet Enabled Ophthalmic Instrumentation

May 5th, 2022

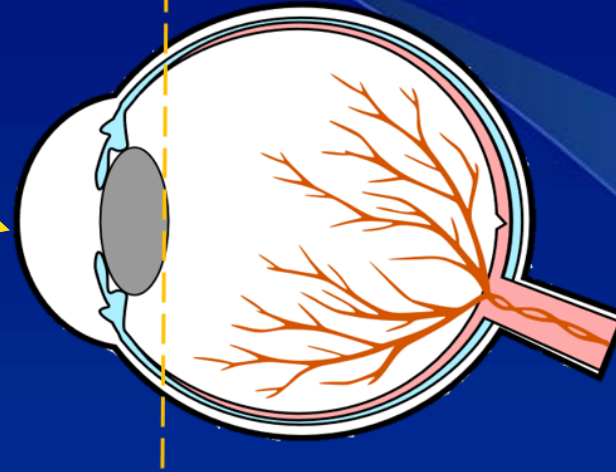
- Presenters:** Benjamin Suen, Mechanical Engineering, Staff
- Researchers:** Dr. Alex Phan, Mechanical Engineering, Project Scientist
Justin Feng, Electrical Engineering, Graduate Student
Zach Daley, Mechanical Engineering, Undergraduate Student
Brian Lee, Mechanical Engineering, Undergraduate Student
- Advisors:** Professor Frank E. Talke, Distinguished Professor, UCSD
Dr. Gerrit Melles, M.D., Ph.D., Ophthalmologist, NIIOS

Stand of Eye Care



Anterior
Segment

Posterior
Segment



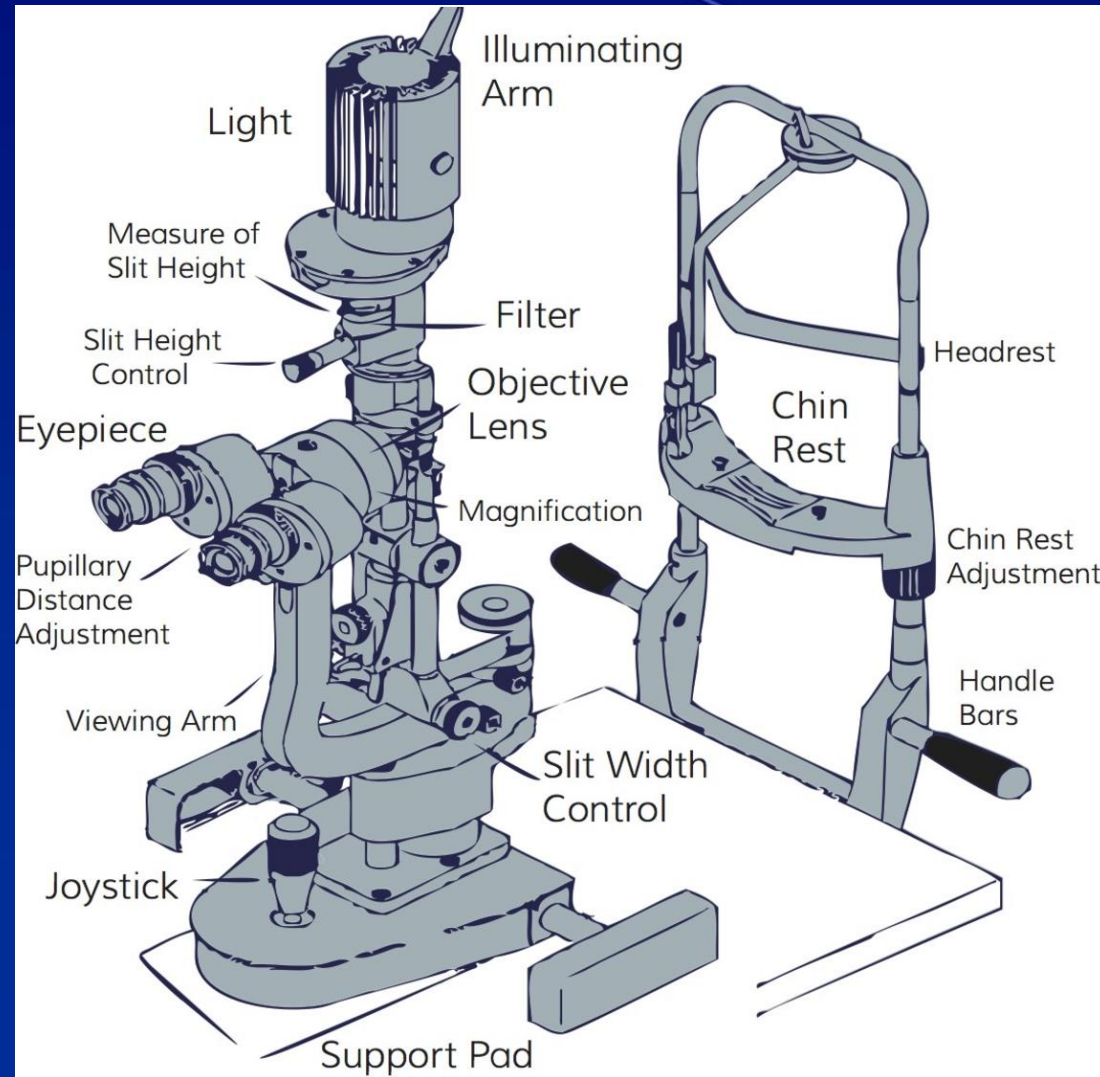
1. High equipment cost
2. Require trained technician
3. Need controlled environment

- Patients need to visit an eye clinic in-person for slit lamp exam
- Such in-person visits are time consuming and costly

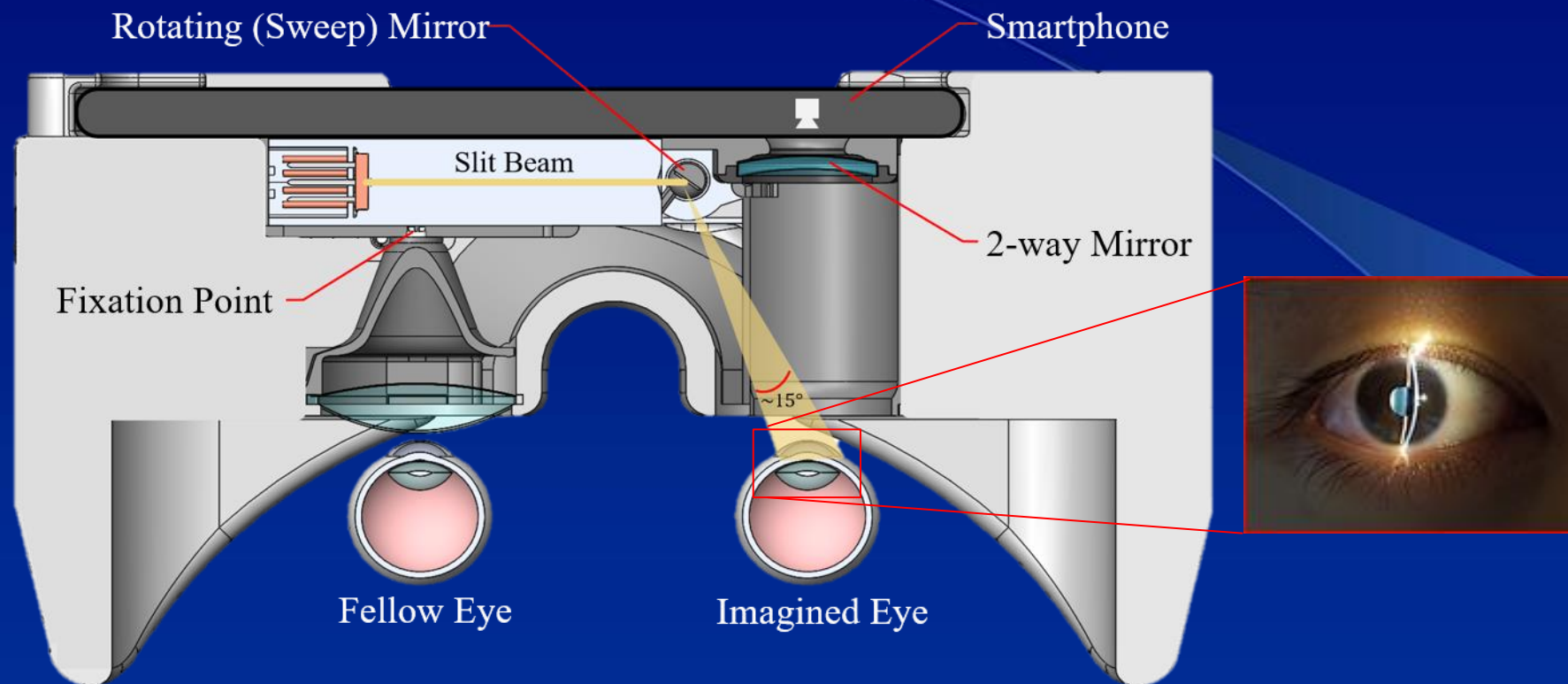
Problem Statement

There is a need for **at-home slit lamp examination** to provide ophthalmologist with **screening results** and save patient from making the time consuming and expensive **visit** to an eye clinic.

Components of a Conventional Slit Lamp

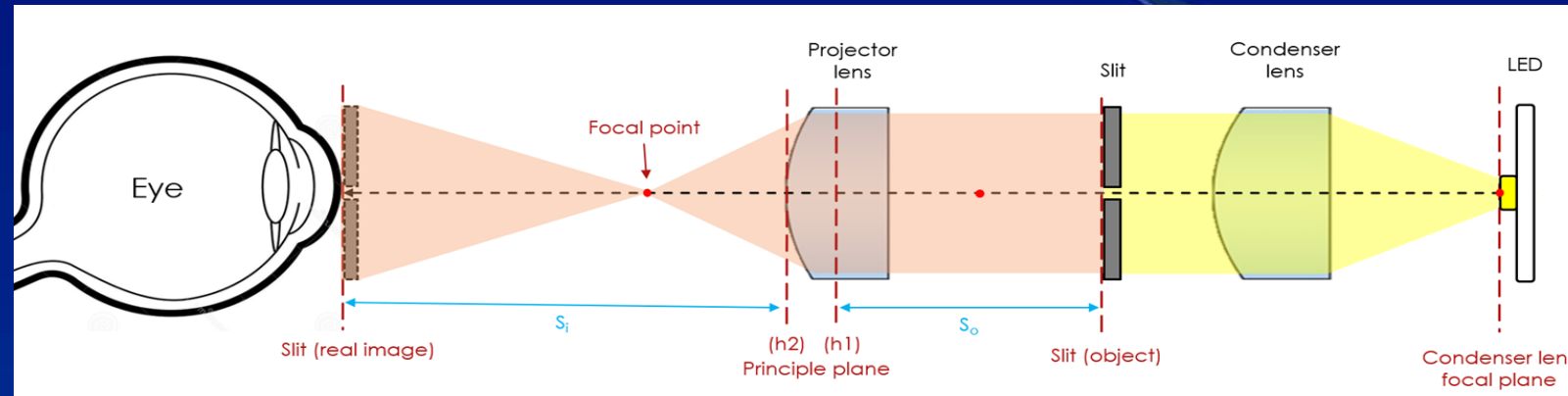


Design of Internet Enabled Slit Lamp



- On the fellow eye: focusing on fixation point helps center the eye
- On the imaged eye: a rotating mirror sweeps the slit beam from one side to the other side of the eye, while the smartphone camera images the eye

Optical Principle of Slit Lamp (Kohler Principle of Illumination)



- Light at the focal point of the condenser lens exits as a defocused beam
- Image of the slit gets projected onto the cornea via projector lens
- Calculate positions of principle planes:

$$h_1 = -\frac{f(n-1)d}{nR_2}$$

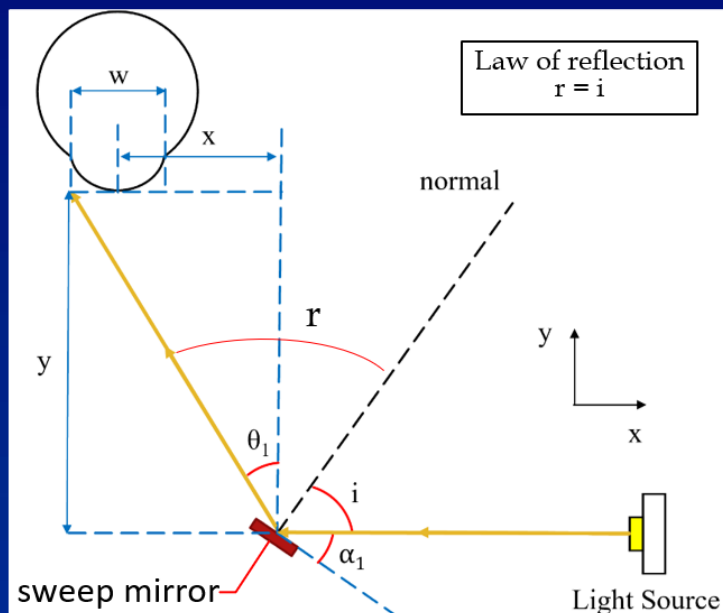
$$h_2 = -\frac{f(n-1)d}{nR_1}$$

- Calculate image distance:

$$\frac{1}{s_o} + \frac{1}{s_i} = \frac{1}{f}$$

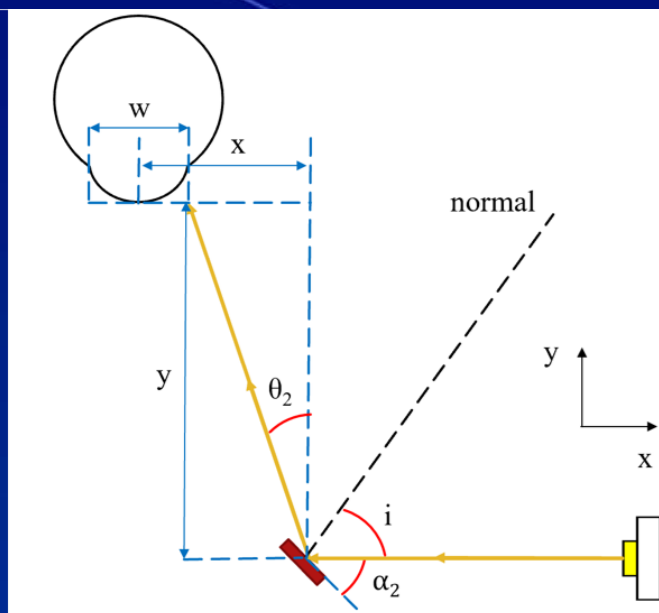
- f = effective focal length
- n = refractive index
- d = thickness of lens
- R = radius of curvature
- s_o = object distance
- s_i = image distance

Auto Sweeping Optical Calculation



$$\theta_1 = \tan^{-1} \left(\frac{x + \frac{w}{2}}{y} \right) \quad (1)$$

$$\alpha_1 = 90^\circ - \left(\frac{\theta_1 + 90^\circ}{2} \right) \quad (2)$$



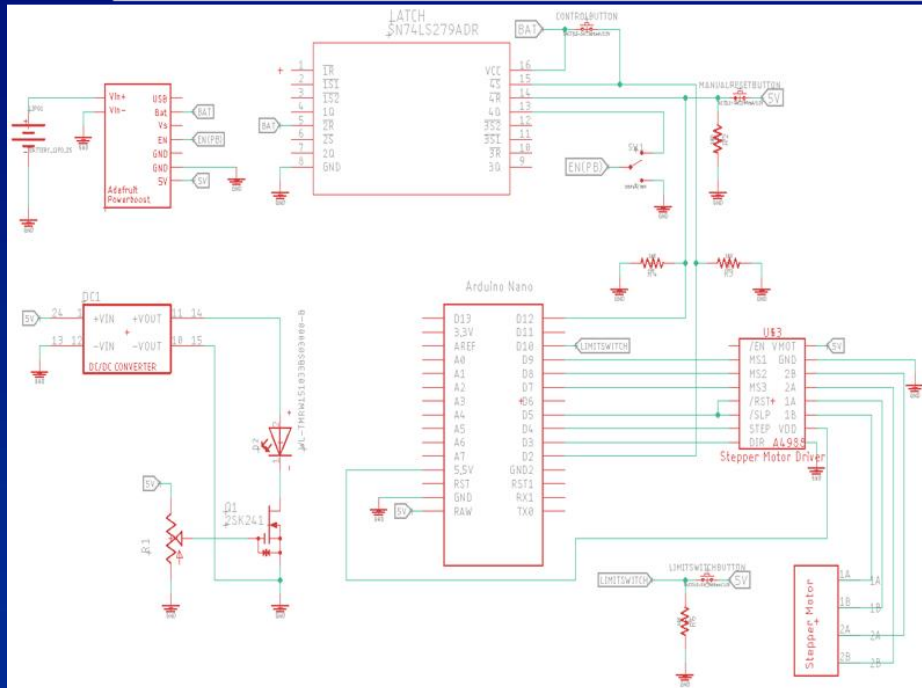
$$\theta_2 = \tan^{-1} \left(\frac{x - \frac{w}{2}}{y} \right) \quad (3)$$

$$\alpha_2 = 90^\circ - \left(\frac{\theta_2 + 90^\circ}{2} \right) \quad (4)$$

β is the sweep range of the mirror

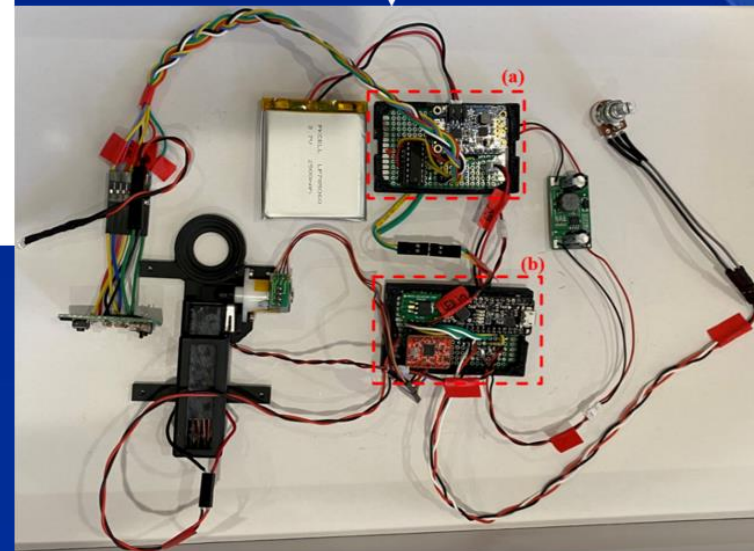
$$\beta = \alpha_2 - \alpha_1 \quad (5)$$

Electrical Circuits

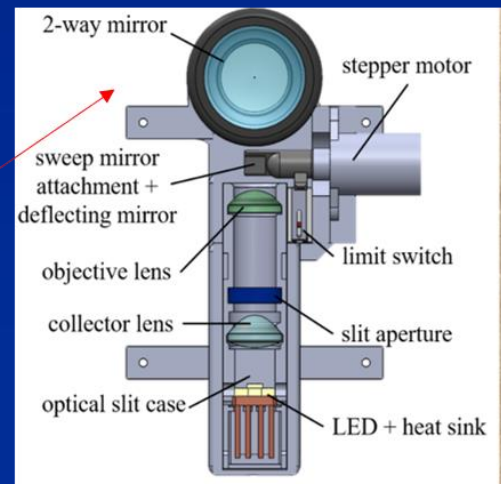
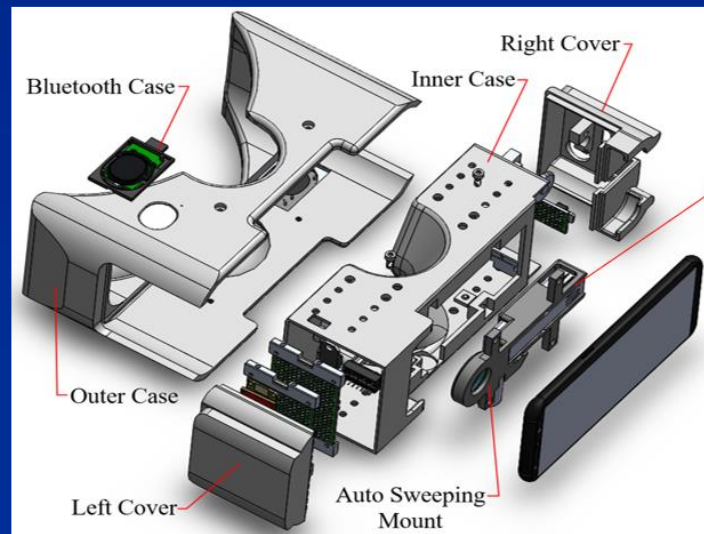


- Microcontroller controls the slit LED and the motor driver
- Dedicated current regulator maintains constant power to the slit LED

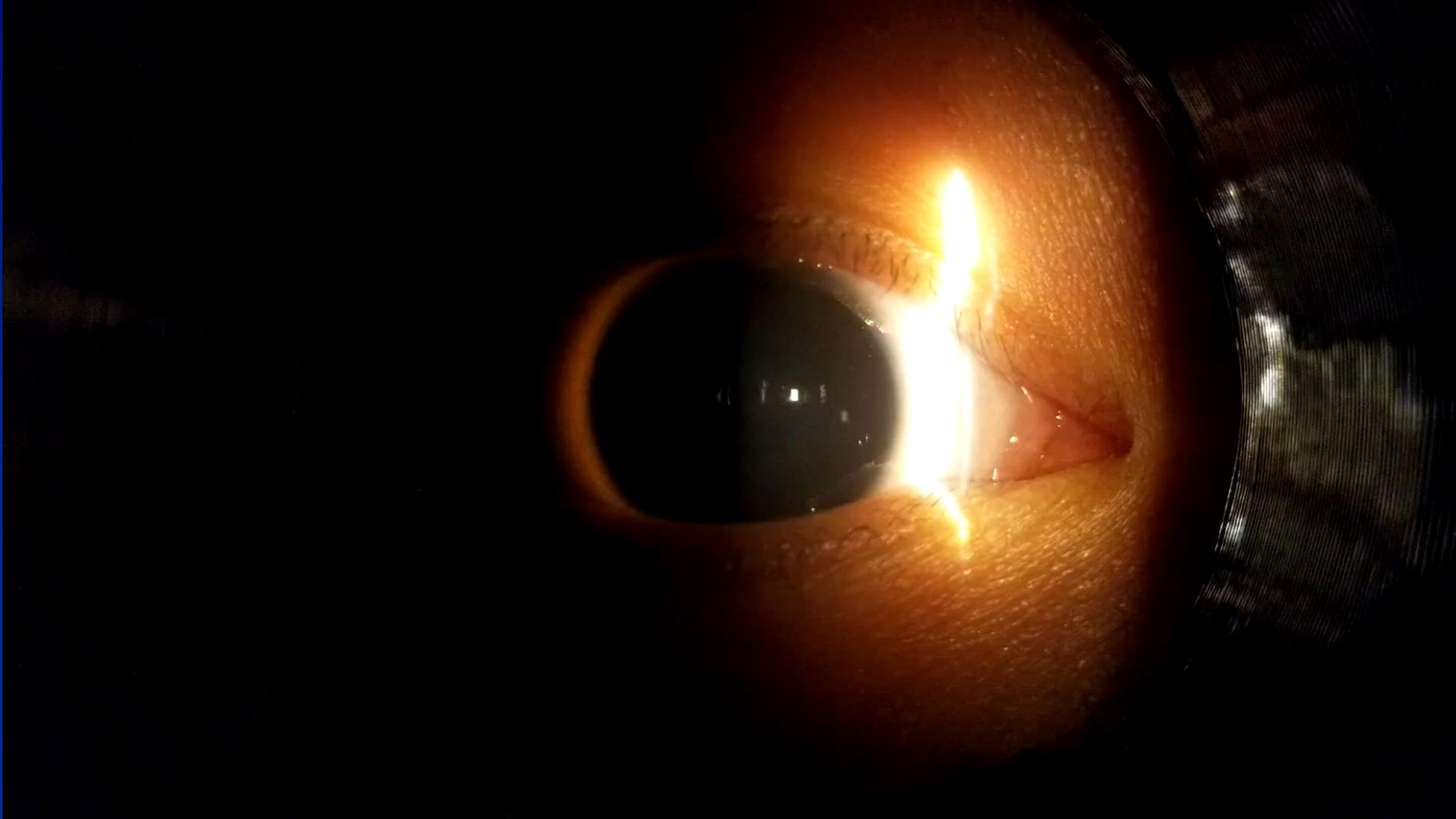
Soldered components onto 2 main prototyping boards



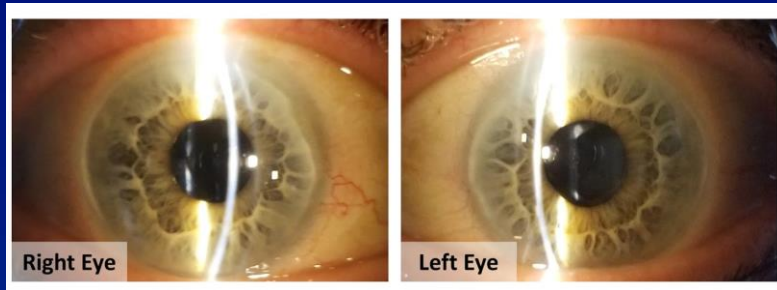
3D Printed Housing



Video of Slit Lamp Sweep

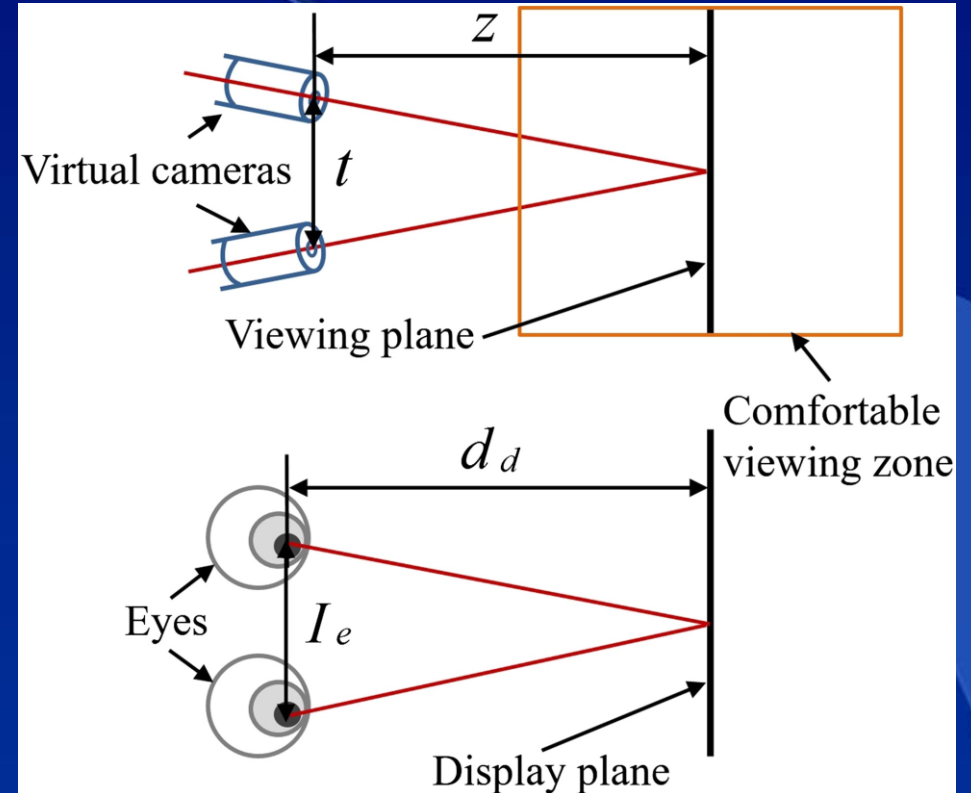
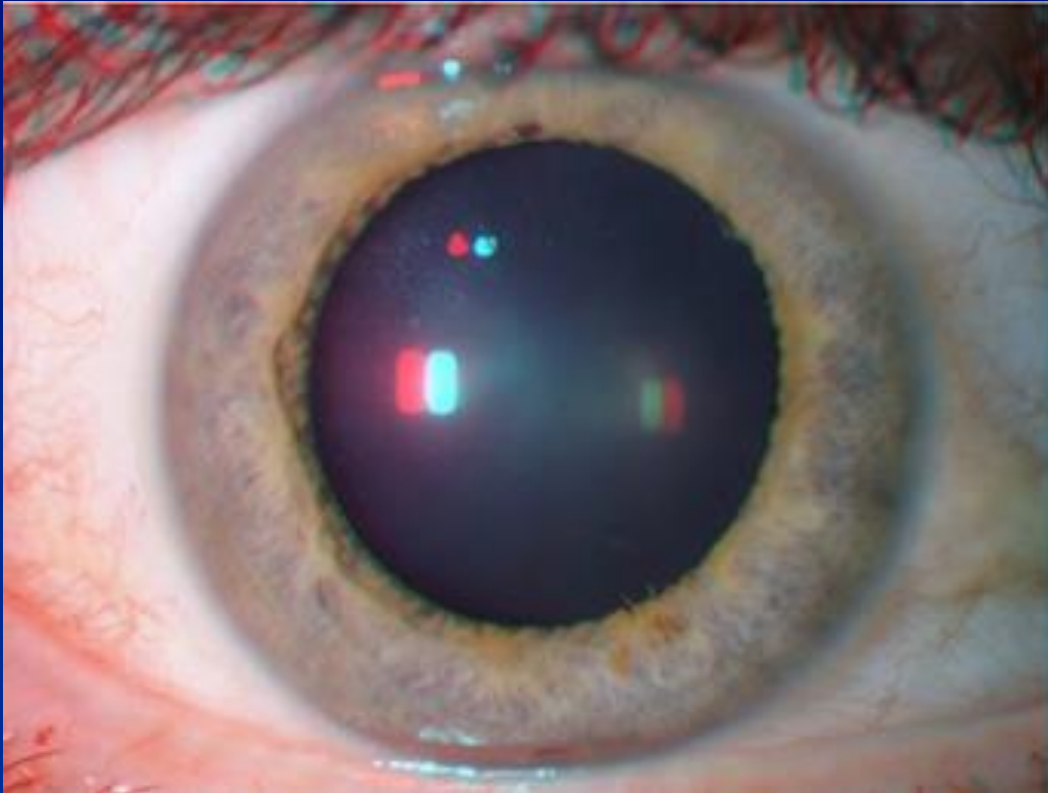


Clinical Results



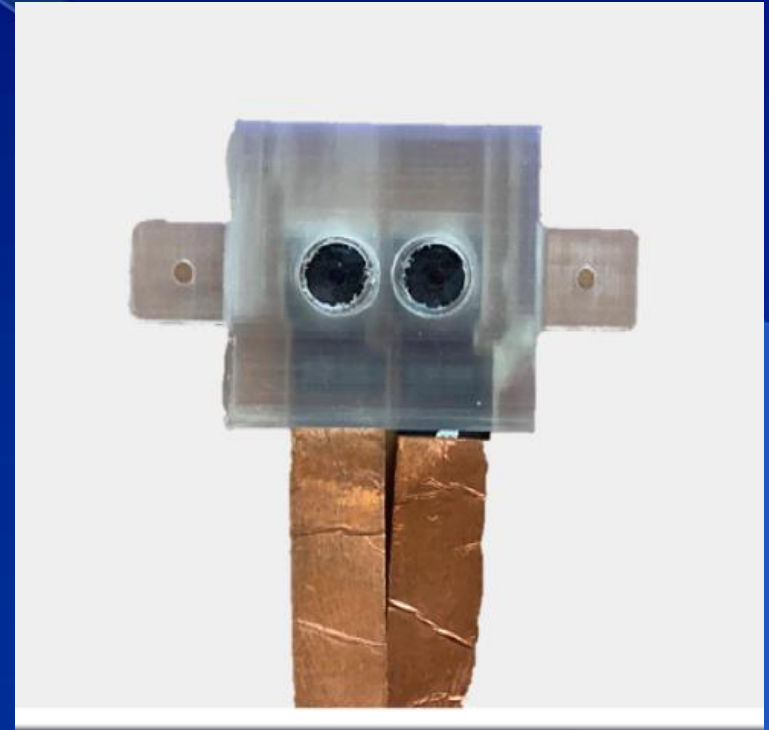
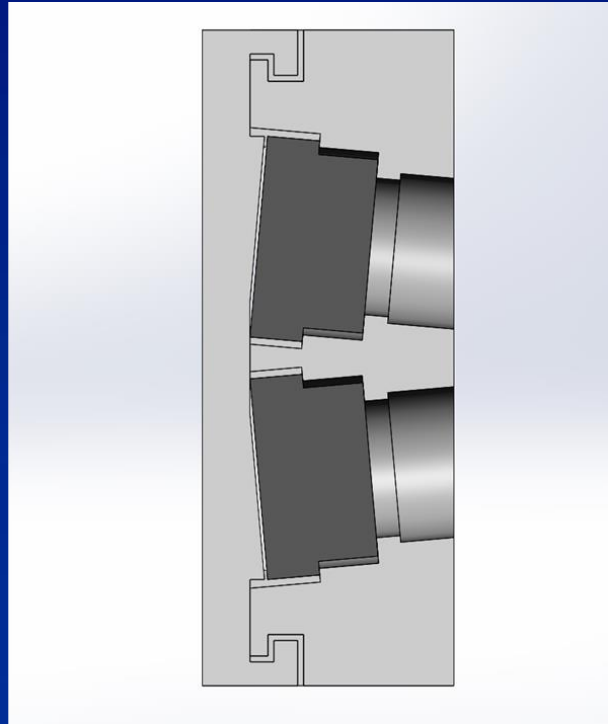
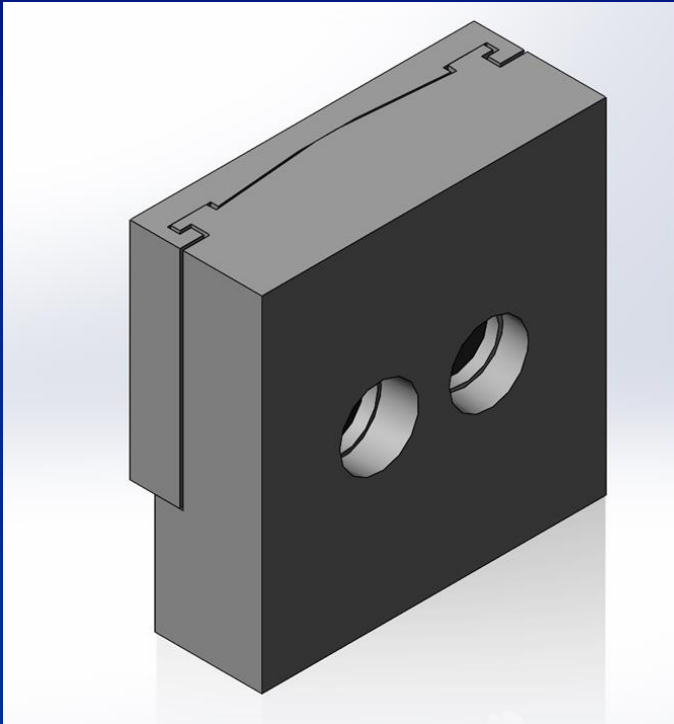
Number of eyes/patients	10/10
Gender (female/male)	5/5
Eye (right/left)	5/5
Mean age in years (+/- standard deviation)	82 (+/-9)
Age range in years	61 - 90
Result	
Quality score out of 5 (1=poor; 5=excellent)	
<ul style="list-style-type: none"> • Video score (+/- standard deviation) • Photo score (+/- standard deviation) 	3.7(+/-0.5) 3.8(+/-0.4)
Ease-of-use score on a 5 points scale	3.7(+/-1.1)

Stereo Anaglyph Image



Gao, Yuanqian, et al. "Modeling the convergence accommodation of stereo vision for binocular endoscopy." *The International Journal of Medical Robotics and Computer Assisted Surgery* 14.1 (2018): e1866.

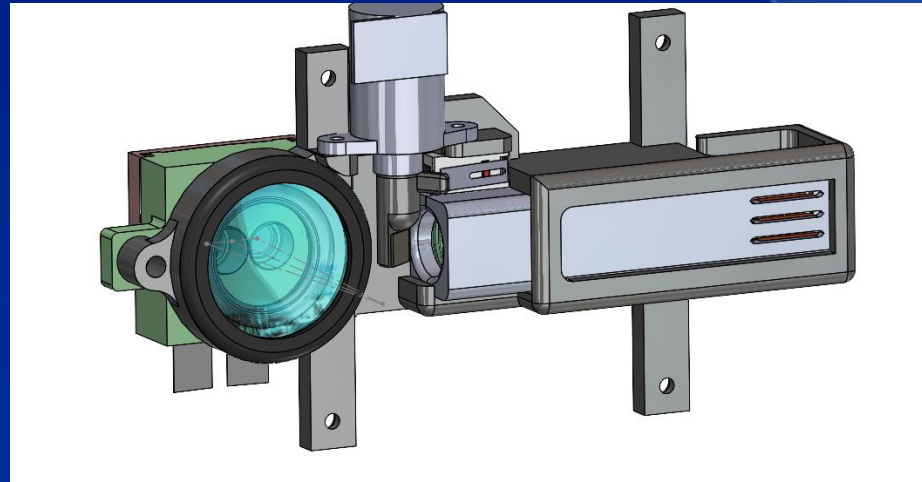
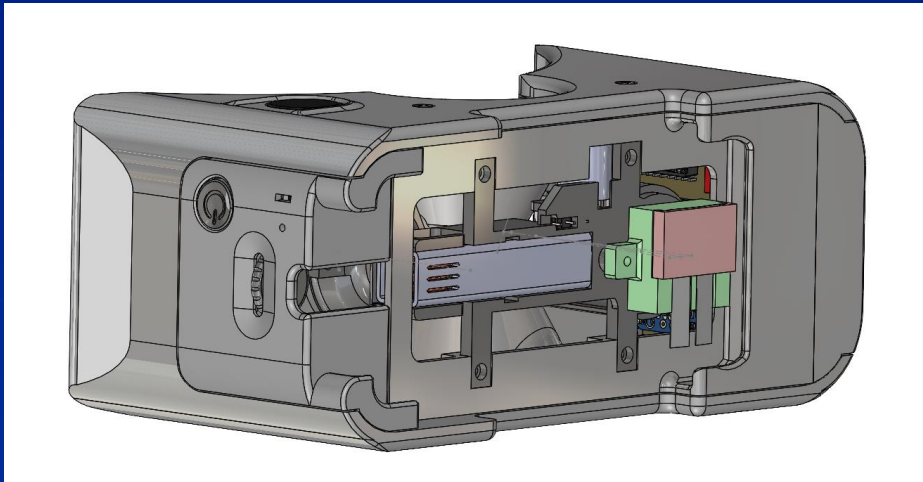
Size & Convergence Angle Optimization



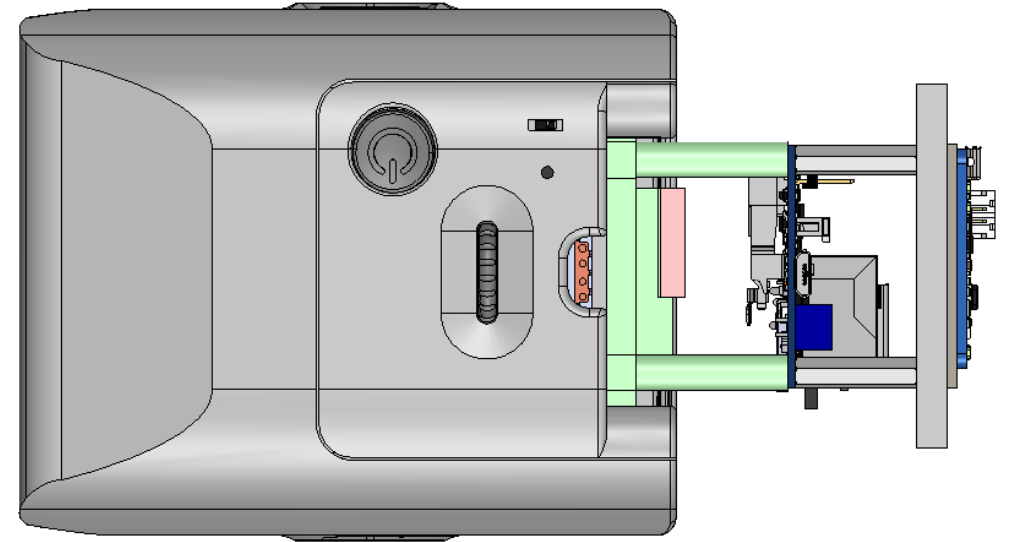
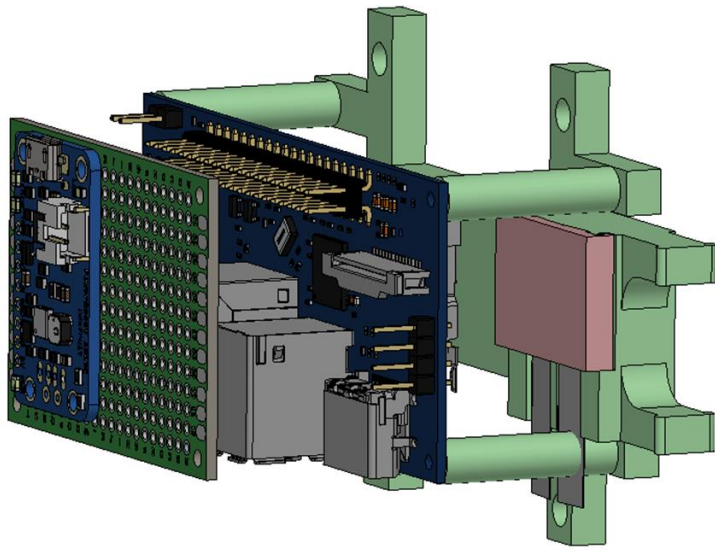
Initial Testing



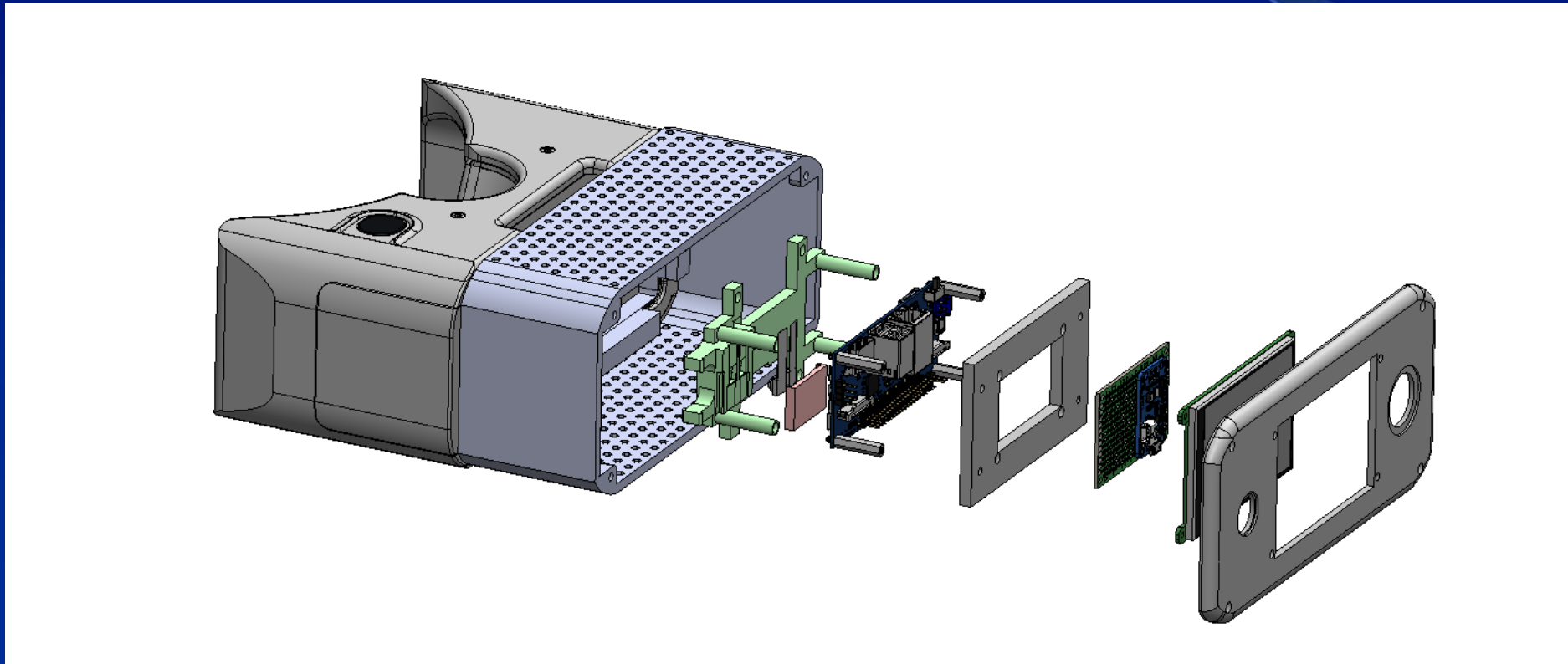
Optics Assembly



Internal Electronics Subassembly



Exploded View of Enclosure



3D Printed Prototype

