3D PRINTED GYROID ELASTOMER AND SILICONE COMPOSITE FOR CONTROLLED ANISOTROPY SIMULATING HUMAN TISSUE

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Outline

- Introduction
- Medical motivation
- Design of a composite material to simulate nonlinearity and anisotropy of human tissue
- Composite Structure
- Experimental data
- Discussion
- Future Work

Introduction

Radiation Induced Vaginal Stenosis



- Common cervical cancer treatment complication
- Treatable with medical intervention
- Change of tissue morphology and properties
 e.g. stiffening of the tissue

Vaginal Tissue Properties

Radiation Induced Vaginal Stenosis



- Variating mechanical properties across the vaginal canal
- Strain stiffening
- Anisotropic

Motivation

Achieving accurate mechanical properties for a vaginal analog is crucial for developing effective treatments and medical devices for gynecological disorders.

Mechanical Properties of Tissue



Strain hardening and anisotropy induced by collagen unraveling and fiber orientation in tissue

Composite for Tissue Analog





Use of geometric structure for strain stiffening and anisotropy

Research Goal

- The goal of this research is to simulate the anisotropic and strain stiffening properties of human tissue.
- The material developed will be used for the design of vaginal phantoms to assist medical device development and training of physicians.

Composite Structure



3D printed TPU scaffolding

Mold with liquid silicone resin Resultant material

3D Printed Scaffolds



$$= sin\left(\frac{2\pi x}{a}\right)cos\left(\frac{2\pi y}{b}\right)$$
$$+sin\left(\frac{2\pi y}{b}\right)cos\left(\frac{2\pi z}{c}\right)$$
$$+sin\left(\frac{2\pi z}{c}\right)cos\left(\frac{2\pi x}{a}\right)$$

- Allows for geometric variation
- Mathematically defined structure
- Tunable geometric anisotropy
- a, b, and c, represents unit cell length

3D Printed Scaffolds



$\mathbf{t} = \sin\left(\frac{2\pi x}{a}\right)\cos\left(\frac{2\pi y}{b}\right) + \sin\left(\frac{2\pi y}{b}\right)\cos\left(\frac{2\pi z}{c}\right) + \sin\left(\frac{2\pi z}{c}\right)\cos\left(\frac{2\pi x}{a}\right)$

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a) Isotropic gyroid structure: a = b = c = 1
b) Anisotropic gyroid structure: a = c = 1, b = 2

Experimental Setup

- Uniaxial tensile tester
- Digital Image Correlation: contactless strain measurement
- High resolution strain and displacement data





Test Coupon Configurations

- 1. Isotropic gyroid
- 2. Anisotropic x-distorted gyroid coupon with a=2, b=1, c=1
- 3. Anisotropic y-distorted gyroid coupon with a=1, b=2, c=1



4. Anisotropic x and y-distorted gyroid coupon with a=2, b=2, c=1

Isotropic Coupon





Isotropic



[121] Anisotropic Isotropic





Summary

- Nonlinear strain-stiffening behavior
- Gyroid controlled anisotropy
 - Coupon [211] showed stiffer stress-strain response despite lower TPU content compared to control
- Coupon [121]'s similar response to isotropic coupons suggests distortions aligning with the direction of applied load account for the majority of behavior
- Coupon [221]'s higher stiffness implies aspect ration of in-plane and out-of-plane gyroid cell size contributes to stress response

Future Work

- FEM studies on gyroid geometry and composite
- Investigation of silicone-gyroid configurations to generate higher strain stiffening rates at smaller deformations.
- 3D deformation study of cylindrical composite vaginal model

Thank you!