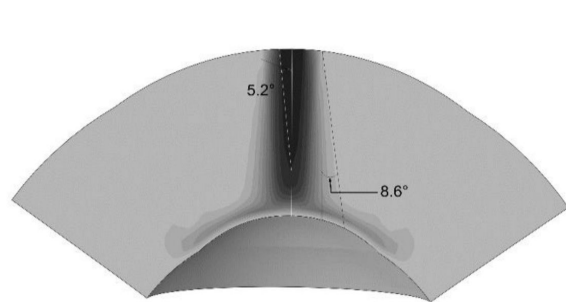
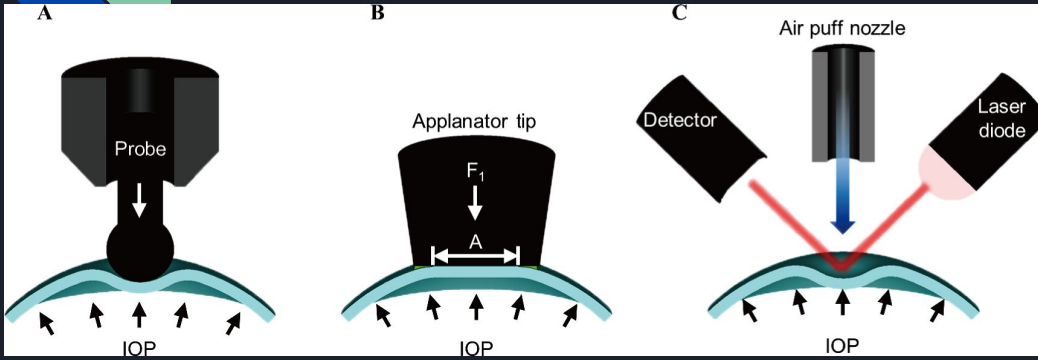




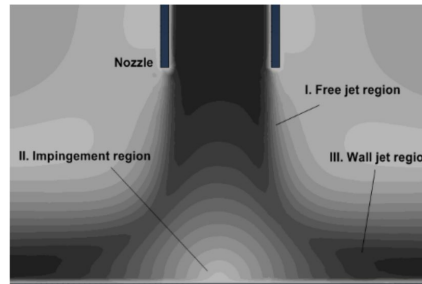
# CMRR Presentation

Zach Daley

# Tonometer Overview



(a)

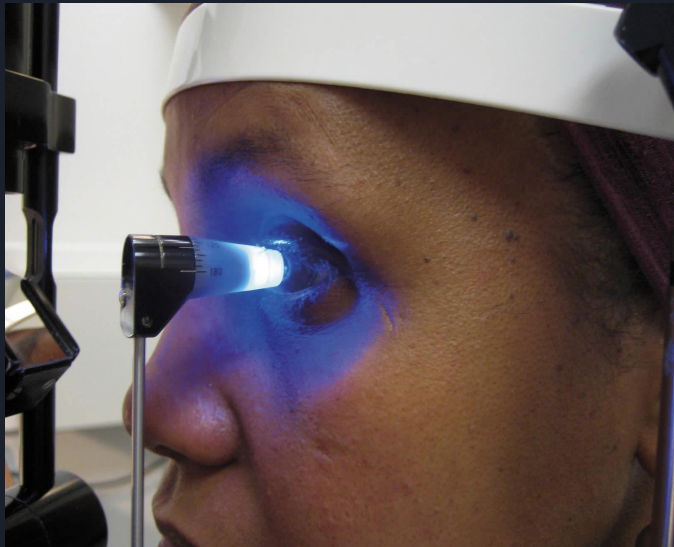


(b)

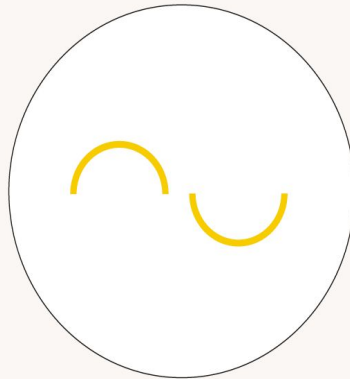
Working principles of conventional intraocular pressure measuring system:

- (i) Applanation tonometer
- (ii) Rebound tonometer
- (iii) Air-puff tonometer

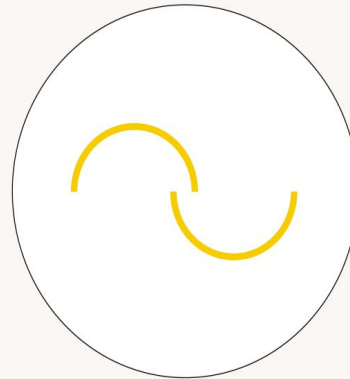
# Goldmann Applanation Tonometry



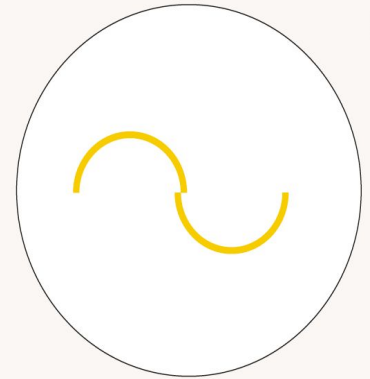
*Figure 1. Applanation tonometry semi-circles viewed through the Goldmann prism*



High intraocular pressure will result in this image. Turn the calibrated dial on the tonometer backwards to reach the accurate end point.

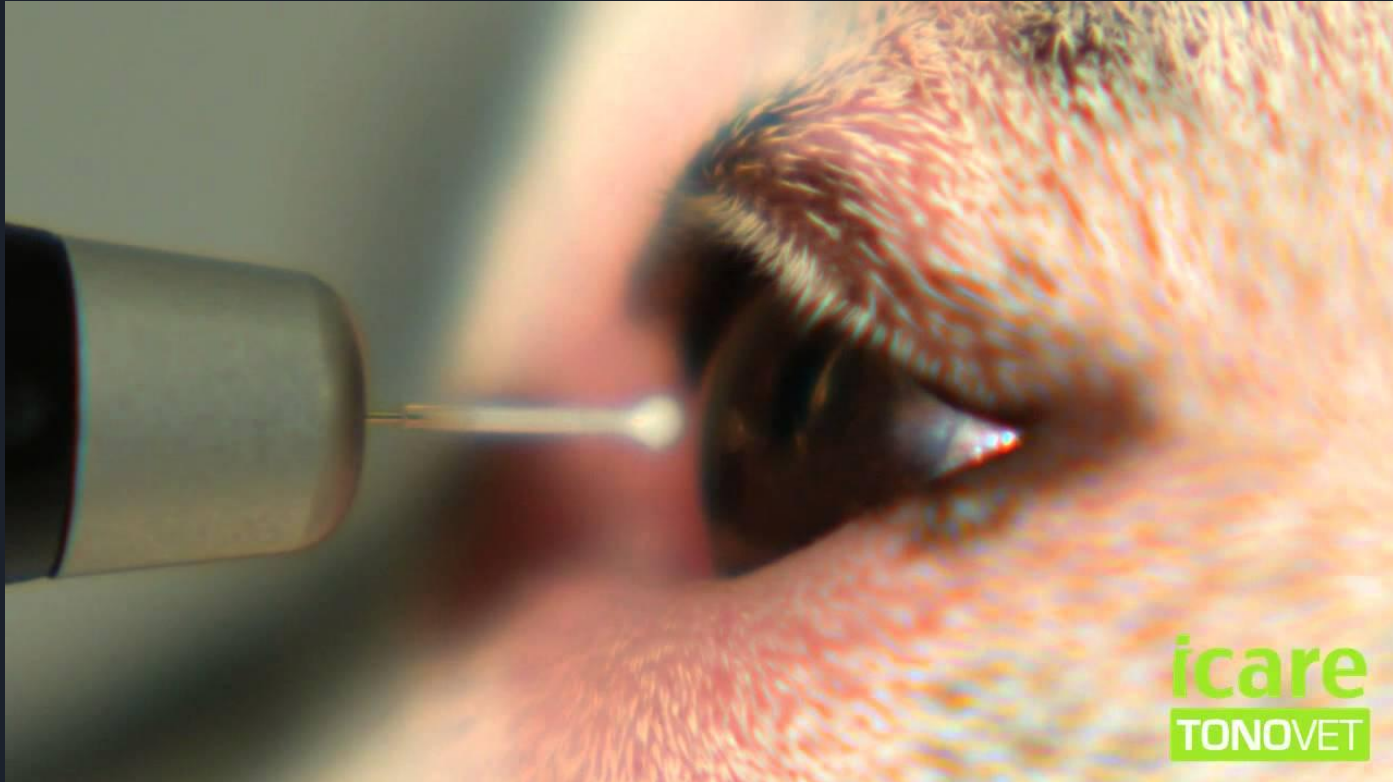


Low intraocular pressure will result in this image. Turn the calibrated dial on the tonometer forwards to reach the accurate end point.

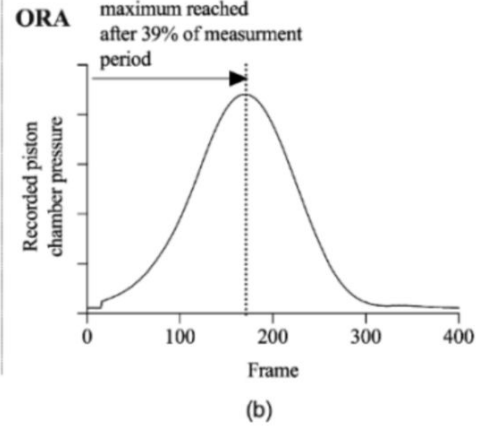
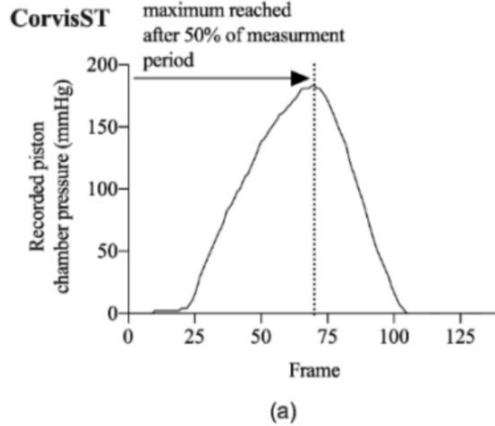


This is the correct end point – the inner edges of the semi-circles are just touching. This will give an accurate reading of intraocular pressure.

# Rebound Tonometers



# Corvis ST Tonometer (Air Puff Tonometer)



Start Pat. Demo. Patient 14.05.1972 Right

Display

	Time	Length	Velocity	IOP	Pachy
Appl 1	6.13 ms	1.77 mm	0.09 m/s	7.5 mmHg	527 μm
Appl 2	23.84 ms	2.13 mm	-0.55 m/s		
Hi Con.	18.32 ms	0.00 mm	0.00 mm	1.17 mm	

Images Highest Concavity

Video 18.32ms

# Talke Air Puff Device

Here we consider that the conical null-screen is a truncated cone with radius  $s$ , height  $h$ , it is oriented along the  $z$ -axis, and its base is located at  $z = 0$ .

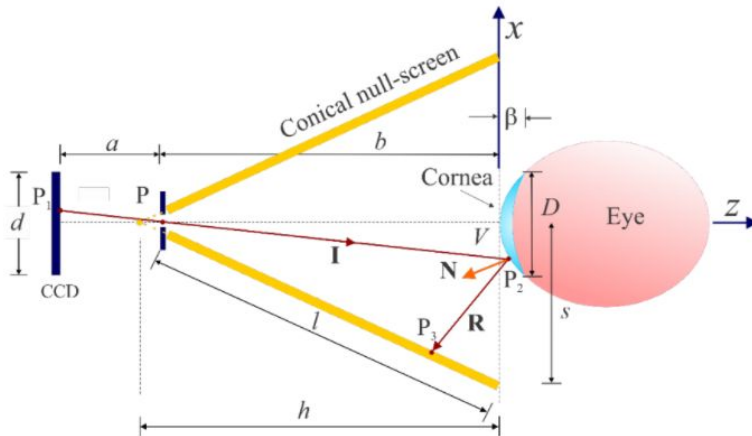
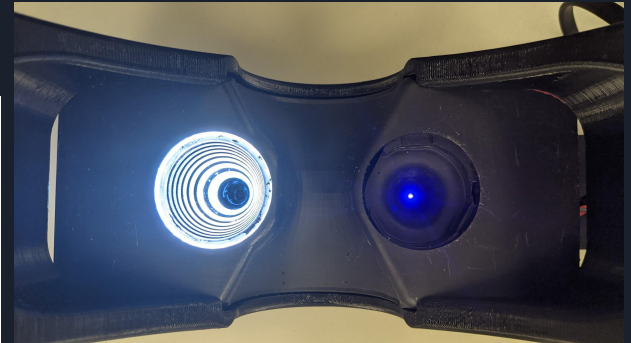
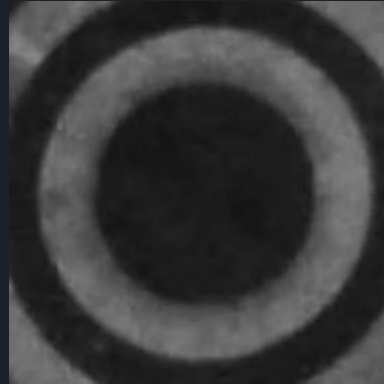
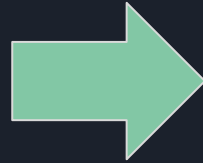


Figure 1. Schematic diagram of the conical corneal null-screen compact topographer.











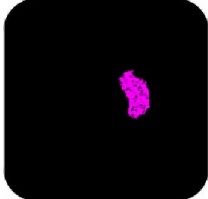


# Extract → Crop Images (Preprocessing)



# K-Means Image Segmentation

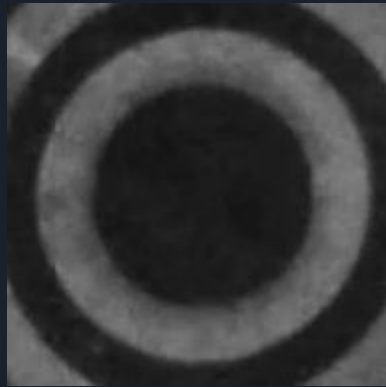
- Unsupervised ML algorithm
- Randomly groups data points with similar brightness values in clusters (shown by same color)
- Useful for detecting distinct features (light rings) from surrounding information

Table 1 Results of Testing Segmentation Program

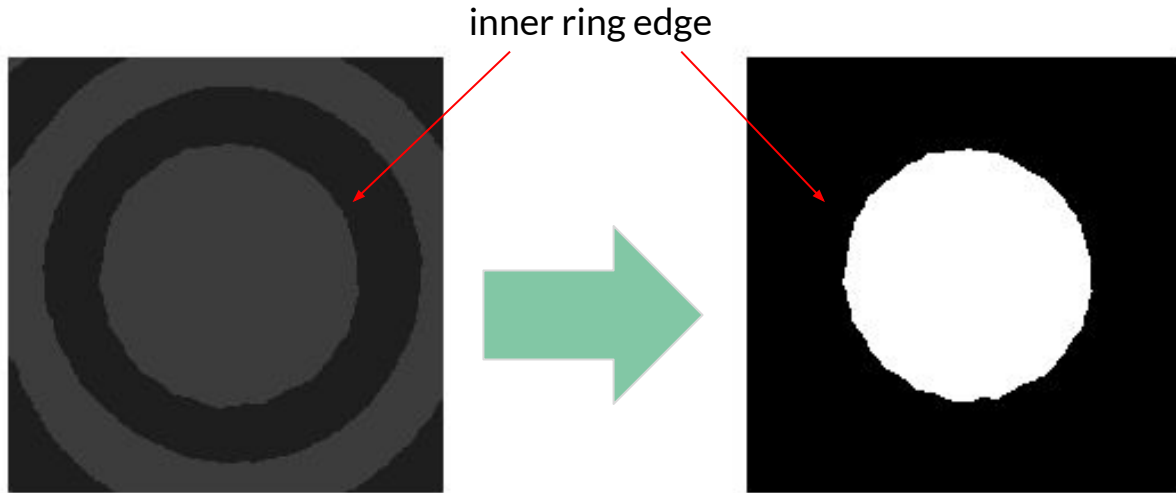
	Image I	Image II	Image III
Input image	 340x406x8b JPEG	 586x586x8b JPEG	 658x777x24b JPEG
Image of Clustering Results			
Image of Thresholding Results			
Processing Time (seconds)	3,17	4,55	5,79



# K-Means Image Segmentation

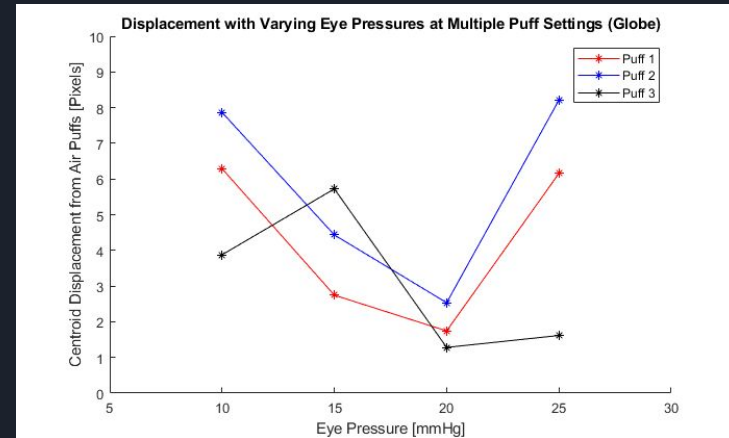
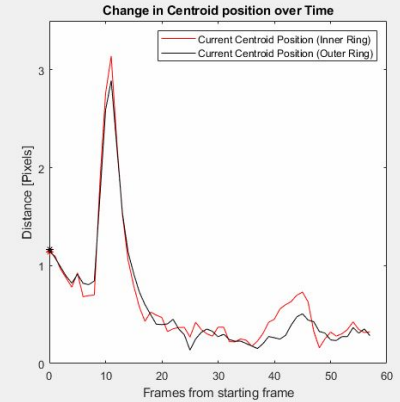
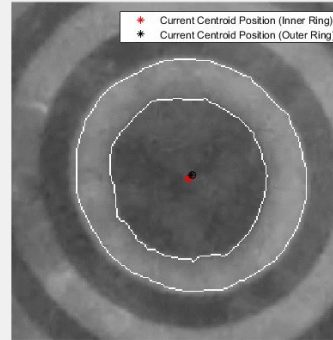


# Isolate Inner Edge of 1st Ring, Make Binary Image



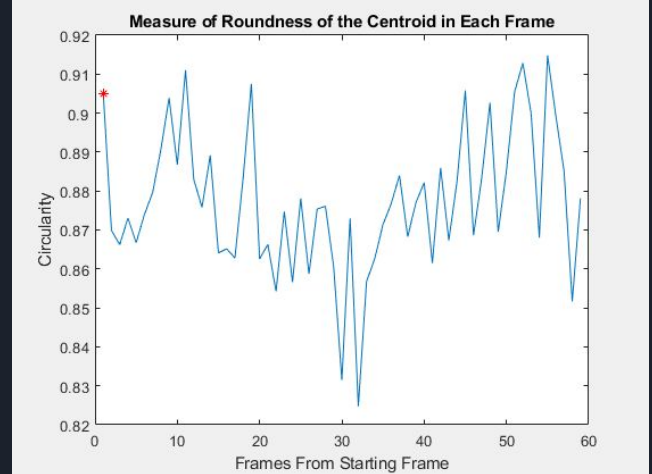
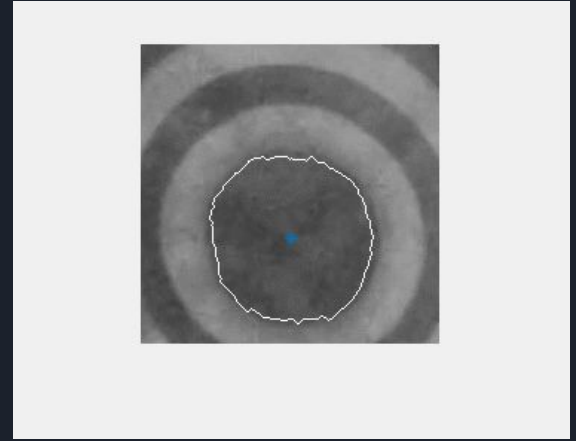
# Metrics of IOP - Centroid Distance from Baseline

- Compares centroid of perimeter to the averaged centroid (obtained by ignoring outliers from air puff frames)
- Strong relationship between IOP and centroid distance

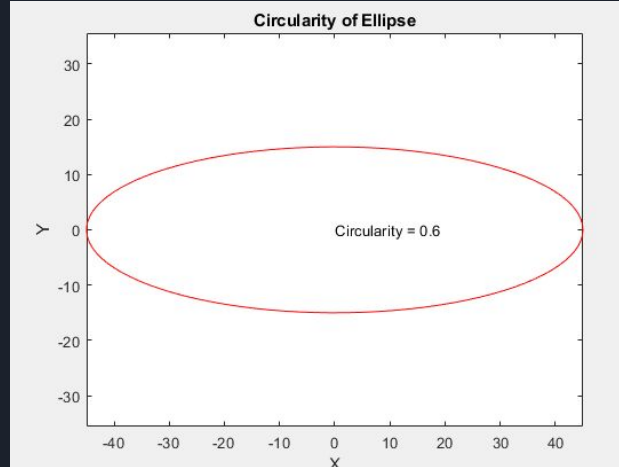
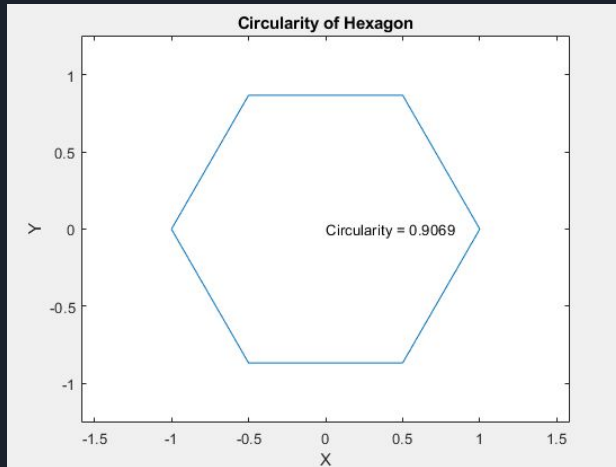
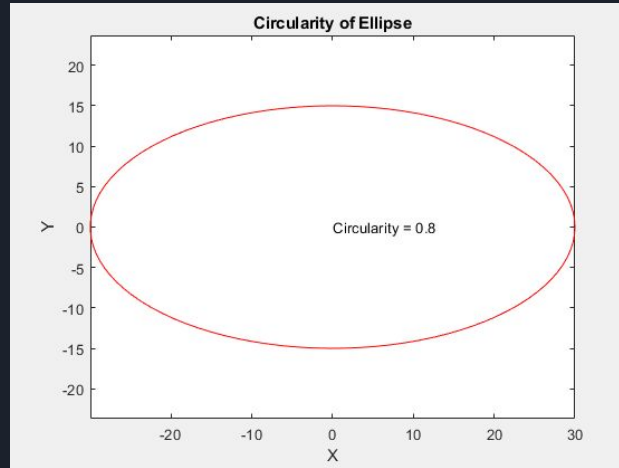
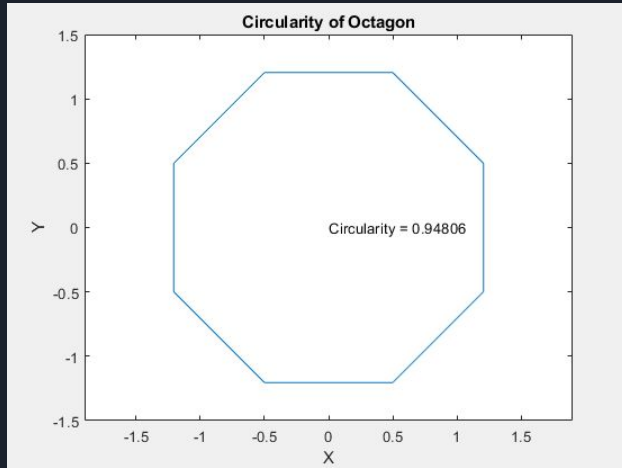


# Metrics of IOP - Circularity

- Roundness is based on the ratio between the inscribed and the circumscribed circles, i.e. the maximum and minimum sizes of circles that fit inside and enclose the shape
- Approximated by  $\frac{2\pi A}{P^2}$
- Strong relationship between IOP and circularity metric at a higher image resolution

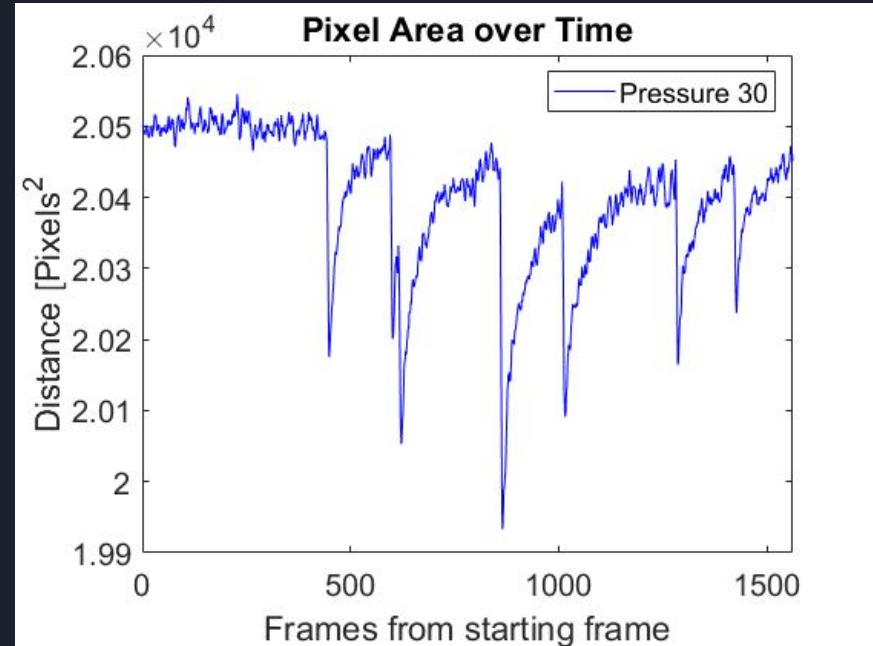


# Metrics of IOP - Circularity



# Metrics of IOP - Area

- Compares the overall area of the rings with the overall area of the rings with the previous frame
- Best relationship between IOP and area metric given our current image resolution due to the enormous changes in area after each air puff





## Next Steps

- Experiment w/ new 3-in-1 device (higher FPS)
- Obtain data from experiments relating IOP to metrics
- Write paper describing device and results